

VACON 1000

Negative sequence compensation

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Three **business segments** geared for growth



Danfoss Power Solutions

#2 Market position

- 7,609 employees
- 28 factories in 13 countries
- 2.0bn EUR annual sales



Danfoss Climate Solutions

#2 Market position

- 10,530 employees
- 34 factories in 15 countries
- 2.5bn EUR annual sales



Danfoss Drives

#2 Market position

- 4,438 employees
- 10 factories in 7 countries
- 1.4bn EUR annual sales



Danfoss Drives business in numbers

Annual revenue

1.4bn

EUR



29m

drives delivered



40m

cars equipped with power modules



1000

partner companies



Global presence

100,50,10

Countries
Sales & service offices
Factories



First mover since

1968



2020 figures


Breadth and depth in **VLT®** products

Low-voltage drives up to 1.4 MW

| | | | | |
|---|---|---|--|---|
|  |  |  |  |  |
| VLT® Micro Drive FC 51 | VLT® Midi Drive FC 280 | VLT® HVAC Basic Drive FC 101 Limited markets | VLT® Automation Drive FC 360 Limited markets | VLT® Lift Drive LD 302 |
|  |  |  |  |  |
| VLT® Refrigeration FC 103 | VLT® Automation Drive FC 301/FC302 | VLT® AQUA Drive FC 202 | VLT® HVAC Drive FC 102 | VLT® Low Harmonic Drive |
| Motor protection | | Brake resistors | | Decentral drives up to 7.5 kW |
|  |  |  |  |  |
| VLT® Advanced Harmonic Filter AHF 005 and AHF 010 | VLT® Advanced Active Filter AAF | VLT® Sine-wave Filter MCC 101 VLT® du/dt Filter MCC 102 VLT® Common Mode Filter MCC 105 | VLT® Brake Resistor MCE 101 | VLT® Decentral Drive FCD 302 |
| Motion drives and gear motors up to 7.5 kW | | Soft starters | | Software |
|  |  |  |  |  |
| VLT® DriveMotor FCP 106 | VLT® OneGearDrive® | VLT® Integrated Servo Drive ISD® 510 System | VLT® Soft Starters | VLT® Software |

Breadth and depth in **VACON®** products

Low-voltage drives up to 6.0 MW

| | | | | |
|--|--|---|--|--|
|  |  |  |  |  |
| VACON® 20 | VACON® 20 Cold Plate | VACON® 100 INDUSTRIAL | VACON® 100 FLOW | VACON® NXP Air Cooled |
|  |  |  |  |  |
| VACON® NXC Air Cooled Enclosed Drives | VACON® NXP Liquid Cooled Drive | VACON® NXP Liquid Cooled Enclosed Drive | VACON® NXP System Drive | VACON® NXP Common DC Bus |
| | | | Harmonic products | Decentral drives up to 37 kW |
|  |  |  |  |  |
| VACON® NXP Liquid Cooled Common DC Bus | VACON® NXP Grid Converter | VACON® NXP DC/DC Converter | VACON® NXC Low Harmonic | VACON® 20 X |
| Medium-voltage drives | | | Software | |
|  |  |  |  |  |
| VACON® 100 X | VACON® 1000 Enclosed Drive | VACON® 3000 Enclosed Drive | VACON® 3000 Enclosed Drive | VACON® Software |

DrivePro® Life Cycle Services



DrivePro® Site Assessment



DrivePro® Start-up



DrivePro® Extended Warranty



DrivePro® Spare Parts



DrivePro® Exchange



DrivePro® Preventive Maintenance



DrivePro® Upgrade



DrivePro® Remote Monitoring

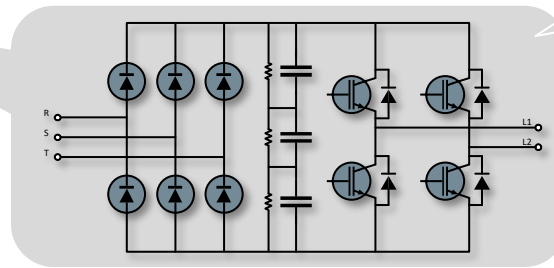
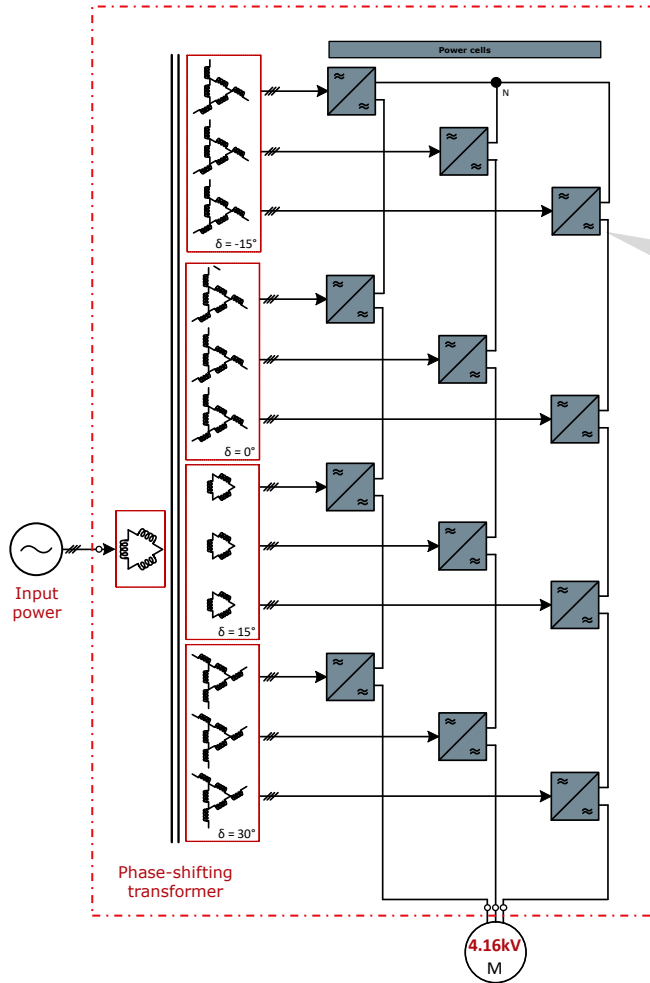


DrivePro® Remote Expert Support



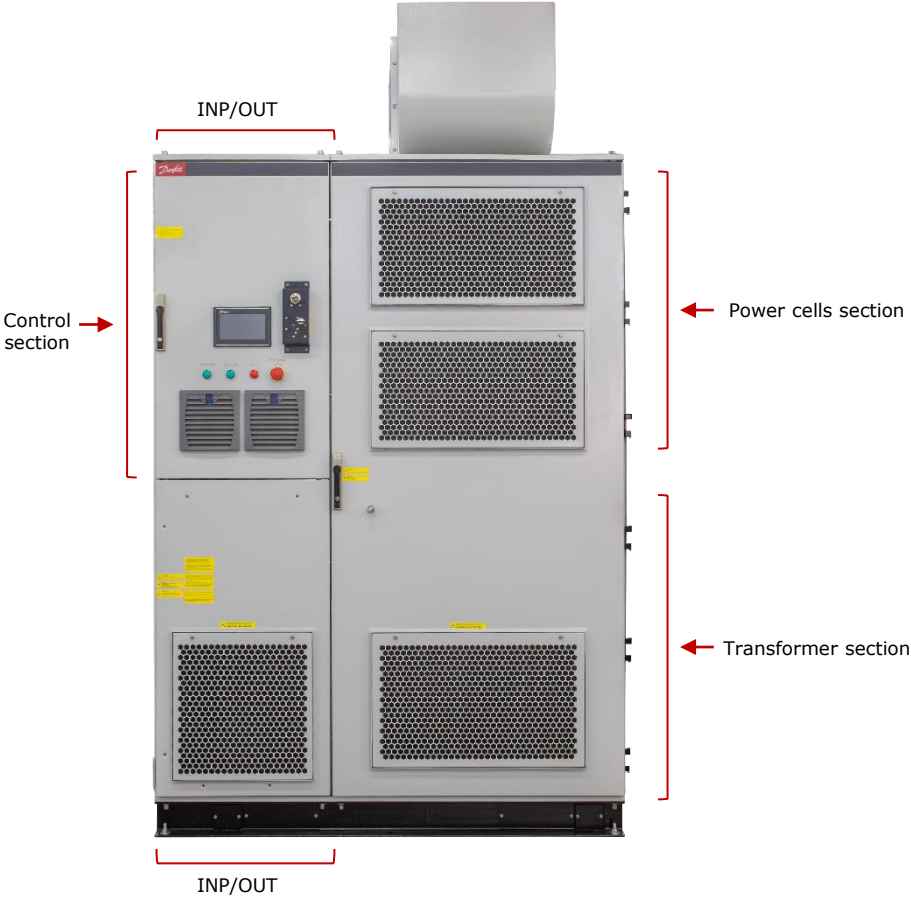
DrivePro® Retrofit

Multi-level Cascaded Inverter



- Modular design
- Series connected power cells
- Multi-level output voltage
- IGBT based power cell bypass (optional)
- N+1 redundant design (optional)
- System bypass (optional)

Stand-alone design structure



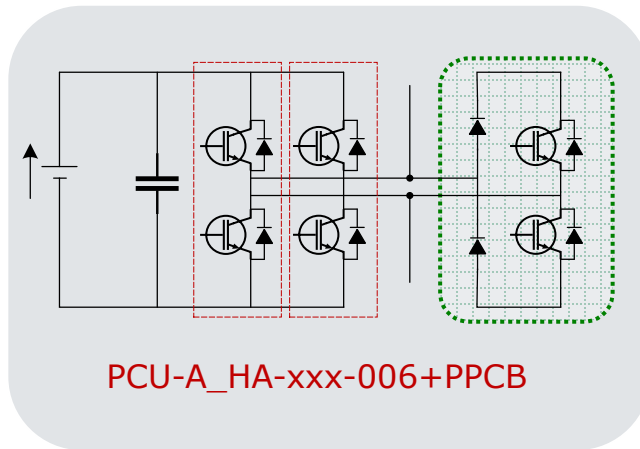
Bypass possibilities

| Bypass type | Bypass device | Drive reactions |
|--|--|---|
| No cell bypass | | Trip |
| Power cell bypass (+PPCB) | IGBT circuit | Continuous operation with voltage drop |
| Power cell redundancy (+PPCR) | As +PPCB, and additional power cell per phase | Continuous operation without voltage drop |
| System bypass Manual (+PMBP) Auto (+PABP) Synchronous (+PSBP) | Manual disconnectors Vacuum contactor Vacuum contactor | Possibility to transfer the load the grid, allowing DOL |

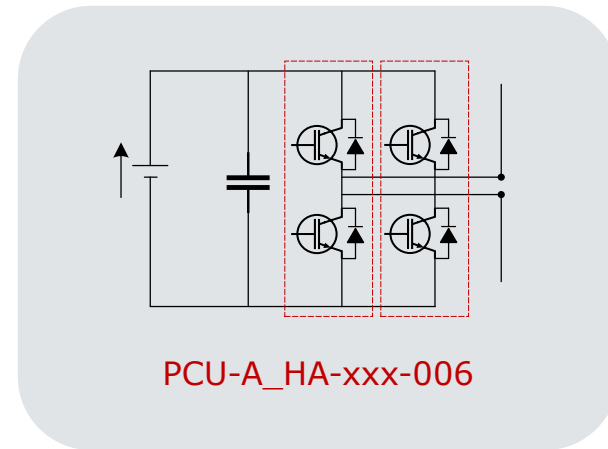
VACON® 1000 **Power cell bypass** (+PPCB)

- Depends on power cell bypass availability
- IGBT type power cell bypass technology - **1ms bypass time**

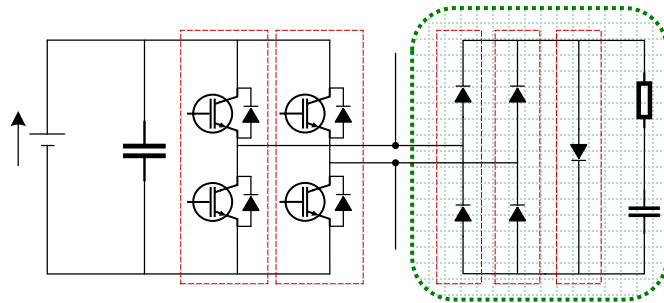
With power cell bypass



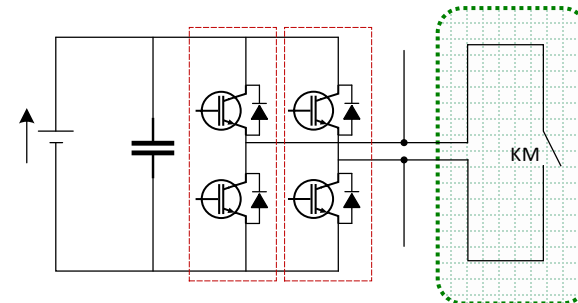
Without power cell bypass



Power cell bypass comparison



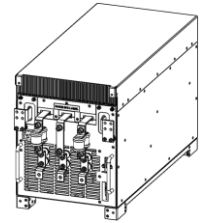
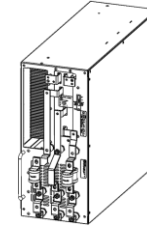
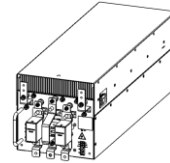
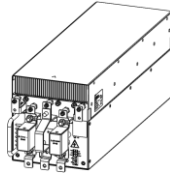
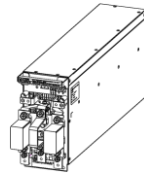
SCR bypass (electronic type)



Contactor bypass (mechanical type)

| Method of bypass | Contactor bypass | SCR bypass | IGBT bypass |
|------------------|-----------------------------|---------------------|----------------------|
| Type of bypass | Mechanical | Electronic | Electronic |
| Reacting time | Slow | Fast | Fast |
| Reliability | Low | Mid | High |
| Remark | Easy to be polluted by dust | Low dV/dt endurance | High dV/dt endurance |

Power cells details



| Type PCU-A2_LA-____-006 | <u>0</u> <u>3</u> <u>6</u> | <u>1</u> <u>0</u> <u>0</u> | <u>1</u> <u>8</u> <u>0</u> | <u>2</u> <u>5</u> <u>0</u> | <u>4</u> <u>3</u> <u>8</u> |
|----------------------------|----------------------------|----------------------------|----------------------------|----------------------------|----------------------------|
| Dimensions | <u>0</u> <u>5</u> <u>0</u> | <u>1</u> <u>4</u> <u>0</u> | <u>2</u> <u>1</u> <u>5</u> | <u>3</u> <u>0</u> <u>5</u> | <u>5</u> <u>6</u> <u>0</u> |
| | <u>0</u> <u>7</u> <u>0</u> | | | <u>3</u> <u>5</u> <u>0</u> | <u>6</u> <u>8</u> <u>0</u> |
| Height [in] | 8.6 | 8.3 | 8.3 | 21.9 | 18.6 |
| Width [in] | 4.4 | 6.5 | 7.5 | 9.7 | 14 |
| Depth [in] | 22.5 | 24.6 | 26.6 | 30.2 | 33.5 |
| Weight [lb] | 46.3 48.6 50.8 | 70.6 72.8 | 88.2 92.6 | 187.4 | 242.6 264.6 286.7 |
| Current [A] | 36 50 70 | 100 140 | 180 215 | 250 305 350 | 438 560 680 |

↑
Stand-alone

↑
Line-up

Power Cells Monitoring HMI Operation Interface

← Status → Power Cell
08/21/2020 21:28:47

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|---|---------------|---|---|---|---|---|---|
| U | Fault Code | 0 | 0 | 0 | 0 | 0 | 0 |
| | Bus Voltage/V | 0 | 0 | 0 | 0 | 0 | 0 |
| V | Fault Code | 0 | 0 | 0 | 0 | 0 | 0 |
| | Bus Voltage/V | 0 | 0 | 0 | 0 | 0 | 0 |
| W | Fault Code | 0 | 0 | 0 | 0 | 0 | 0 |
| | Bus Voltage/V | 0 | 0 | 0 | 0 | 0 | 0 |

Fault Code

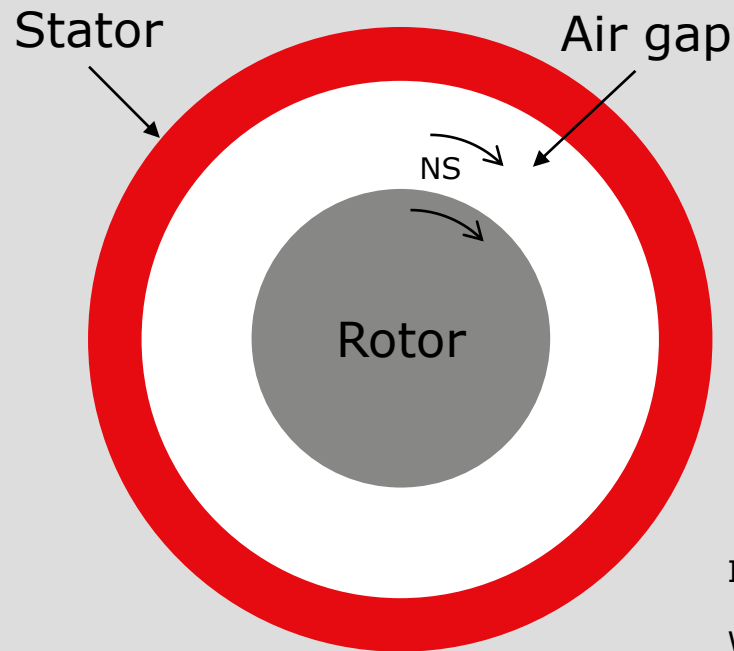
| | | |
|----------------------|----------------------------------|---------------------------------|
| 0: Normal | 5: IGBT Driver Fault | 12: Ultra Over Voltage |
| 1: Power Cell Bypass | 6: Input Phase Loss | 13: DC 24V Power Fault |
| 2: Reserved | 7: Downstream Optical Link Fault | 14: Capacitor Fault |
| 3: Under Voltage | 8: Over Voltage | 14-30: Reserved |
| 4: Over Temperature | 9-11: Reserved | 31: Upstream Optical Link Fault |

Unbalanced supply

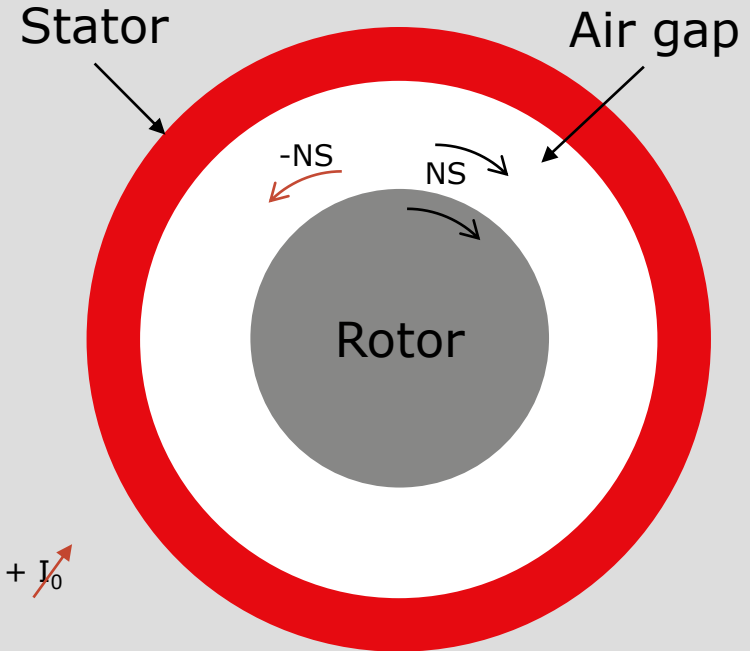
- Balanced supply voltage

- Unbalanced supply voltage

AC motor cross-sectional view



NS = Synchronous speed



$$I = I_1 + I_2 + I_0$$

Where:

I_1 = positive sequence

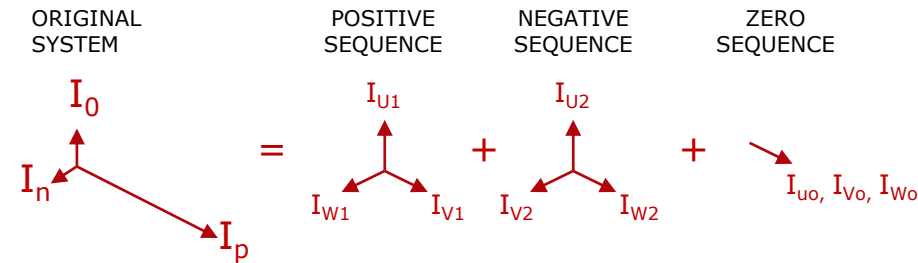
I_2 = negative sequence

I_0 = zero sequence (only present if ground fault)

Negative Sequence Compensation

Description

- When the modulation ratio is above the maximum modulation ratio parameter, the drive output speed is decreased automatically after power cell bypass occurs, namely bypass derating. Therefore, the actual motor speed becomes lower than the specified speed.
- When the modulation ratio is lower than the maximum modulation ratio, bypass derating is finished.
- The operating thresholds of negative sequence compensation are:
 - Minimum operating power factor for negative sequence compensation
 - Minimum operating speed for negative sequence compensation
- When the power factor or output speed is below the thresholds, the drive works in symmetrical bypass mode.



Symmetrical components: positive-, negative- and zero-sequence

Negative Sequence Compensation

Limitations

| Motor output voltage | Motor voltage with one power cell bypassed [%] | Motor voltage with two power cells bypassed in different phase [%] | Max qty of power cell bypassed [qty] | Lowest output voltage when max qty is bypassed [%] | How many power cells from the same phase can be bypassed |
|----------------------|--|--|--------------------------------------|--|--|
| 2300 V (9 cells) | 84.4 | 72.6 | 3 | 64.1 | 1 |
| 2400 V (9 cells) | 80.5 | 69.2 | 3 | 61.2 | 1 |
| 3000 V (9 cells) | 91.4 | 78.6 | 3 | 69.4 | 1 |
| 3300 V (9 cells) | 82.8 | 71.2 | 3 | 62.9 | 1 |
| 4000 V (12 cells) | 87.5 | 79.1 | 3 | 72.1 | 1 |
| 4160 V (12 cells) | 84.3 | 76.2 | 3 | 69.4 | 1 |
| 6000 V (15 cells) | 86 | 79.7 | 6 | 55.6 | 2 |
| 6300 V (18 cells) | 93.2 | 87.6 | 6 | 66 | 2 |
| 6600 V (18 cells) | 88.8 | 83.5 | 6 | 62.9 | 2 |
| 6900 V (18 cells) | 90.5 | 85.1 | 6 | 64.1 | 2 |
| 10000 V (24 cells) | 84.7 | 80.9 | 9 | 55.3 | 3 |
| 11000 V (27 cells) | 87.4 | 84 | 9 | 60.6 | 3 |

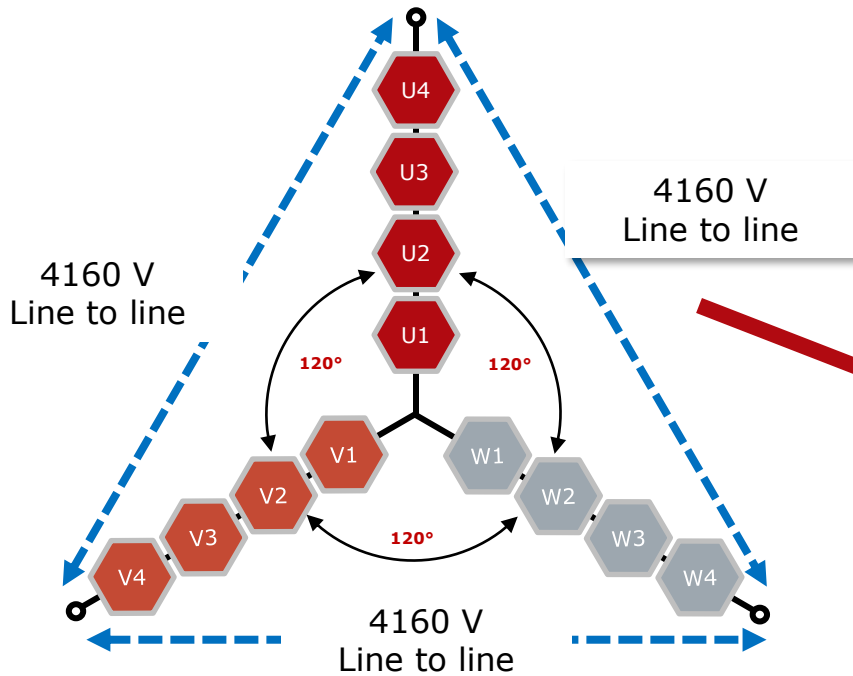
Negative Sequence Compensation

Limitations

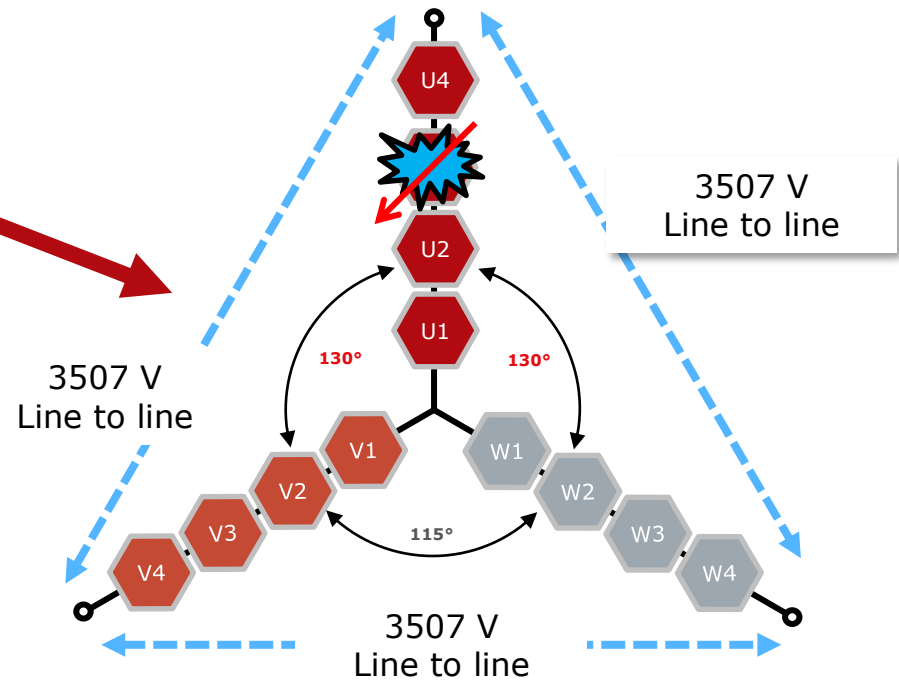
| Motor output voltage | Motor voltage with one power cell bypassed [%] | Motor voltage with two power cells bypassed in different phase [%] | Max qty of power cell bypassed [qty] | Lowest output voltage when max qty is bypassed [%] | How many power cells from the same phase can be bypassed per phase |
|--------------------------|--|--|--------------------------------------|--|--|
| 2300 V (9 cells) | 84.4 | 72.6 | 3 | 64.1 | 1 |
| 2400 V (9 cells) | 80.5 | 69.2 | 3 | 61.2 | 1 |
| 3000 V (9 cells) | 91.4 | 78.6 | 3 | 69.4 | 1 |
| 3300 V (9 cells) | 82.8 | 71.2 | 3 | 62.9 | 1 |
| 4000 V (12 cells) | 87.5 | 79.1 | 3 | 72.1 | 1 |
| 4160 V (12 cells) | 84.3 (3507 V) | 76.2 (3170V) | 3 | 69.4 (2887 V) | 1 |
| 6000 V (15 cells) | 86 | 79.7 | 6 | 55.6 | 2 |
| 6300 V (18 cells) | 93.2 | 87.6 | 6 | 66 | 2 |
| 6600 V (18 cells) | 88.8 | 83.5 | 6 | 62.9 | 2 |
| 6900 V (18 cells) | 90.5 | 85.1 | 6 | 64.1 | 2 |
| 10000 V (24 cells) | 84.7 | 80.9 | 9 | 55.3 | 3 |
| 11000 V (27 cells) | 87.4 | 84 | 9 | 60.6 | 3 |

Negative Sequence Compensation

Power cell bypass (+PPCB)



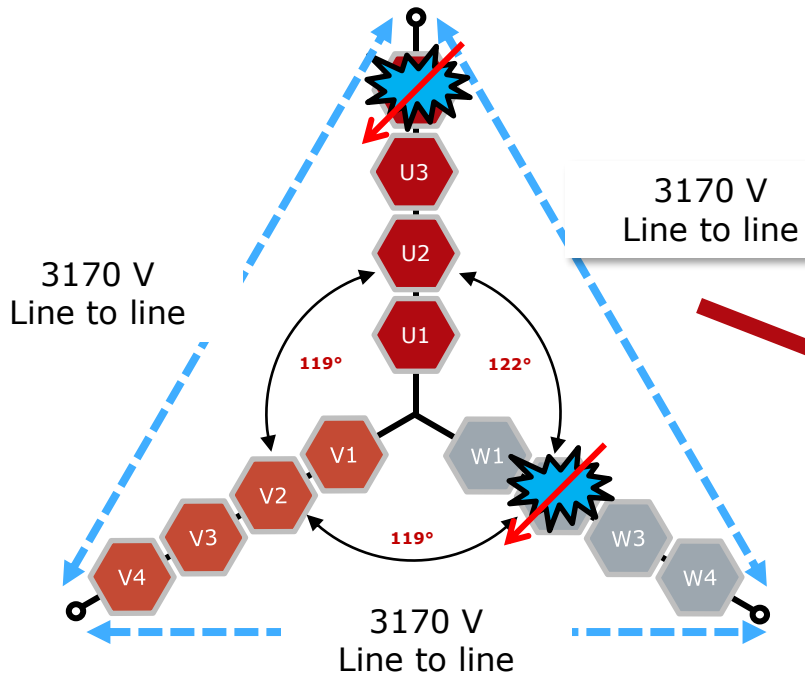
4.16 kV, normal operation



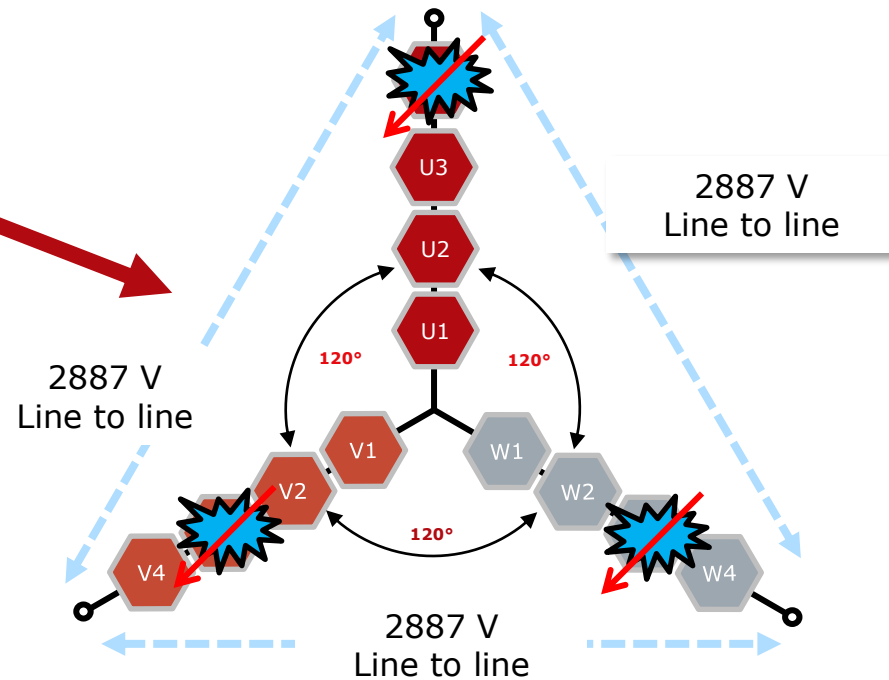
4.16 kV, with one power cell faulty and bypassed

Negative Sequence Compensation

Power cell bypass (+PPCB)



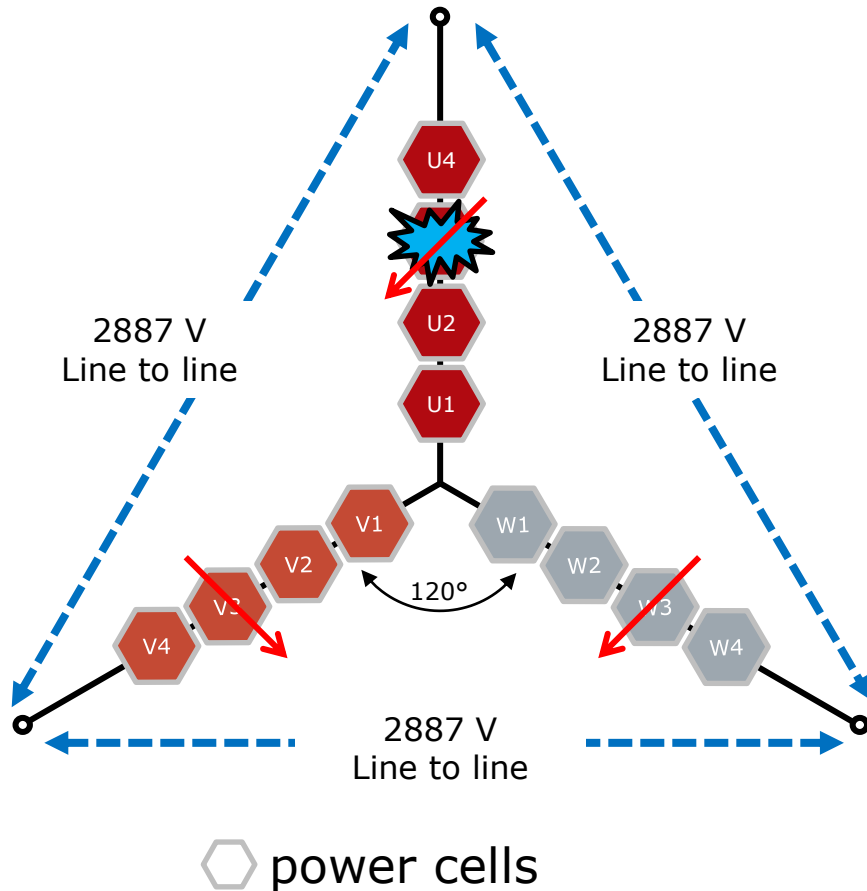
4.16 kV, with two power cell faulty and bypassed



4.16 kV, with three power cell faulty and bypassed

Symmetrical bypass mode

Power cell bypass (+PPCB)



- When the power factor or output speed is below the thresholds, the drive operates in symmetrical bypass mode

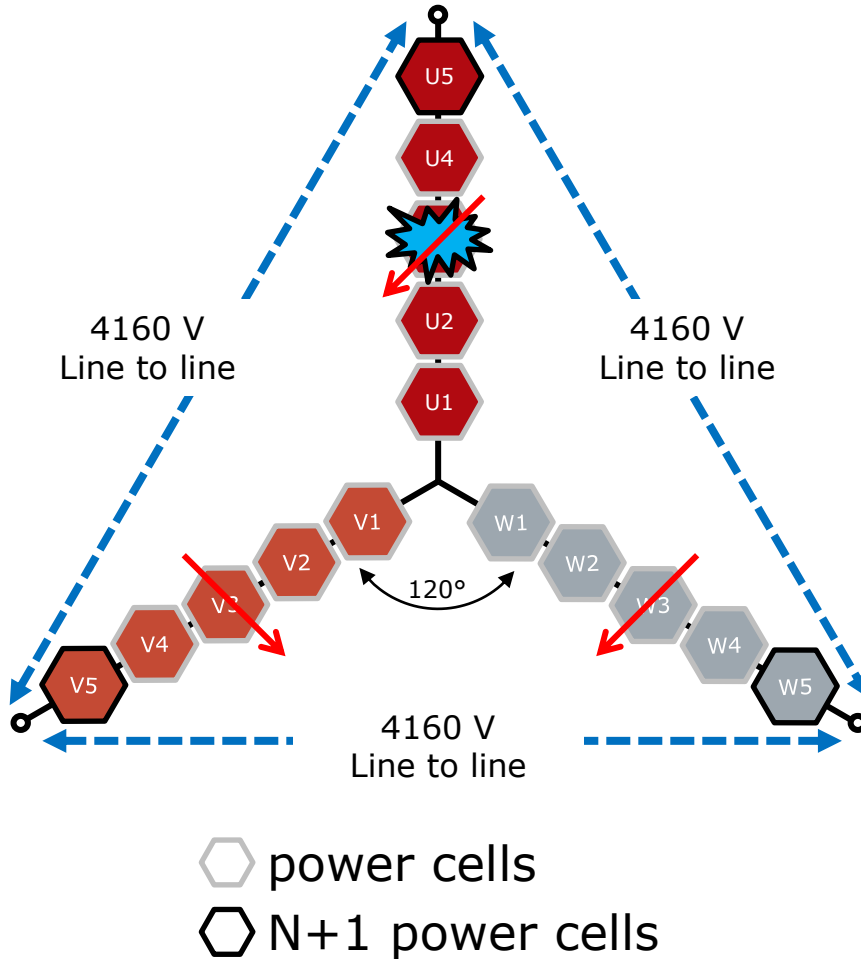
Maximum output power

Output Power 100%

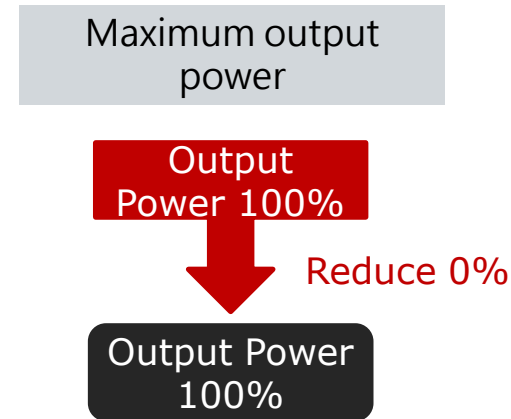
Reduce ~25%

Output Power ~75%

Power cell redundancy (+PPCR)



- Implement one more power cell in each phase
- When power cell bypass function is on, the MVD can still output 100% power without power de-rating
- The output voltage is equally distributed to each power cell before and after power cell bypass



Unbalanced supply consequences

- Induction motors
 - 5% unbalance can cause the reduction in the motor power by 25%
 - even if the induction motor continues to get the rated current before unbalancing.
 - This reduced electrical power of the induction motor attributes to heating in the rotor.
 - The unbalance present in the VFD output by 3% can increase the rotor heating by approximately 20%.
- The VFD will balance the output voltage to reduce losses in the motor
- The VFD will provide proper protection against the unbalanced currents in induction motors

Your best supplier

THE AC DRIVES PARTNER WHO SHARES YOUR GOALS

First mover

in mass production of drives



Financially robust



Global presence



World leader

for installed base

#1

Equip differently

with the motor and fieldbus of your choice



Simplified purchasing





ENGINEERING
TOMORROW